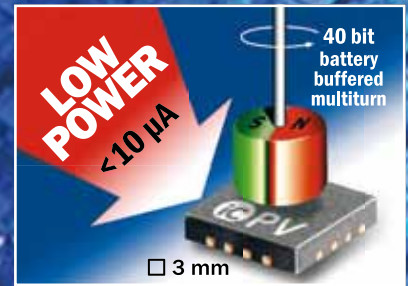


iC-PV BATTERY-BUFFERED HALL-MULTITURN ENCODER



iC-PV is an ultra-low power magnetic encoder with up to 40 bit multiturn (revolution counting) and 3 bit singleturn resolution reading a cylindrical, diametric permanent magnet. The Hall signal processing is designed for battery operation at low power consumption, but can also be configured to track angle acceleration exceeding 500 000 rad/s² and speed beyond 100,000 rpm.

Together with an additional singleturn encoder, such as iC-MHM, iC-LGC or iC-LNB for instance, a complete multiturn position sensor can be built. Furthermore, iC-PV offers 3-bit position data at parallel outputs to support microcontroller operated systems.

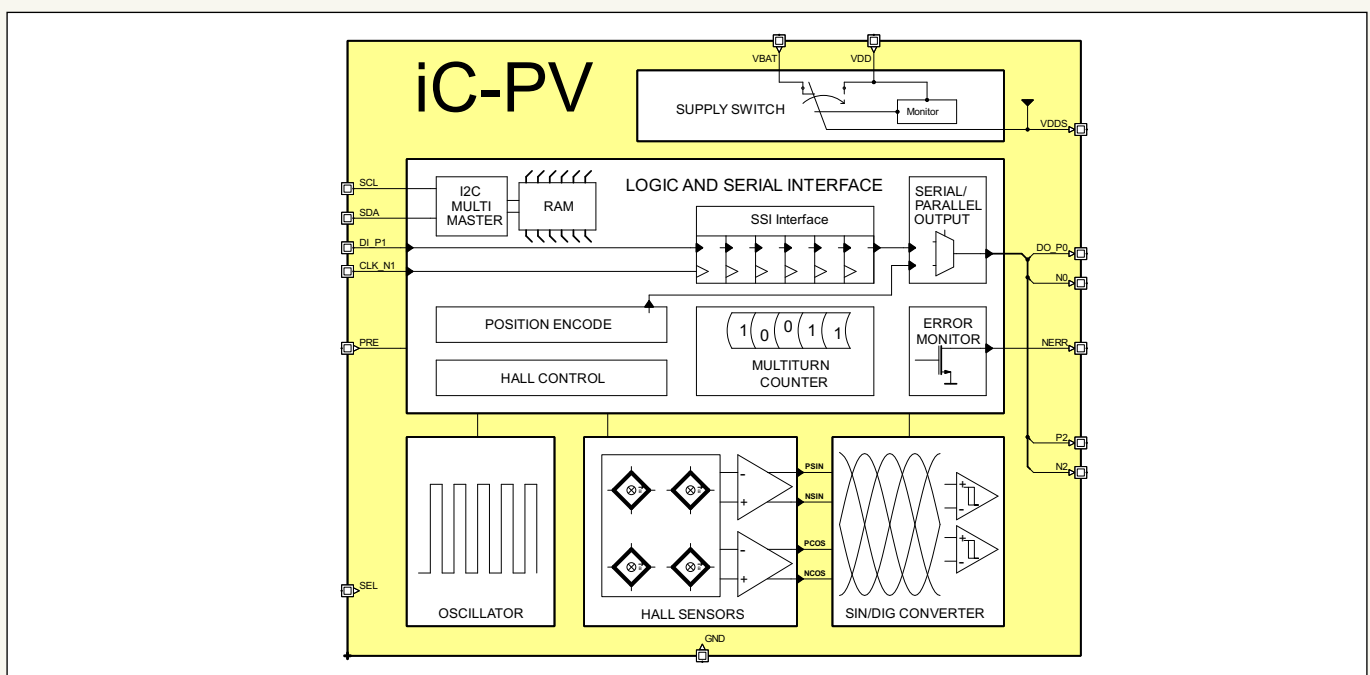
Via its multi-master capable I²C interface iC-PV can source its startup configuration from the EEPROM available to the system.

Features

- Integrated Hall sensors with auto-gain and offset control
- Adjustable performance of tracking (12,000 to 100,000 rpm) versus power consumption (2 μ A to 30 μ A in average)
- Configurable multiturn counting of up to 40 bits
- Octal encoder mode (singleturn) with 3-bit parallel output
- Shift-register input for singleturn position
- Shift-register output of synchronized MT/ST position
- SSI multiturn data output with error, parity, and sync. bits
- Adjustable multiturn preset value
- Pin-triggered preset and boot-up from external EEPROM
- I²C multi-master interface to read EEPROM
- Supply voltage range of 3.0 V to 5.5 V
- Integrated supply switching to backup battery
- Error output on overspeed, low battery, and CRC failure
- Space-saving 16-pin QFN package

Applications

- Gearless revolution counting
- Metering applications
- Absolute end-of-shaft position sensors
- Multiturn encoders



iC-PV BATTERY-BUFFERED HALL-MULTITURN ENCODER

Key Specifications

General

| | |
|--------------------------------|------------------------|
| Main Supply Voltage VDD | single 3 V to 5.5 V |
| Main Supply Current VDD | typ. 3.0 mA |
| Battery Supply Voltage VBAT | 3.0 V to 5.5 V |
| Battery Supply Current I(VBAT) | < 10 μ A (@ 3.3 V) |
| Operational Temperature Range | -40 °C to +125 °C |

Assembly Tolerances Sensor to Magnet

| \varnothing Magnet | Distance | Radial Displacement |
|----------------------|--------------|---------------------|
| 3 mm | up to 4.0 mm | up to 1.0 mm |
| 4 mm | up to 6.0 mm | up to 1.5 mm |
| 8 mm | up to 7.0 mm | up to 3.0 mm |

Hall Array Dimensions/Signal Conditioning

| | |
|--------------------------------|--------------------------------|
| Diameter of Hall Sensor Circle | 1.75 mm |
| Magnetic Field Strength | 10 to 100 kA/m |
| Magnetic Input Frequency | 2 kHz max. (up to 120 000 rpm) |

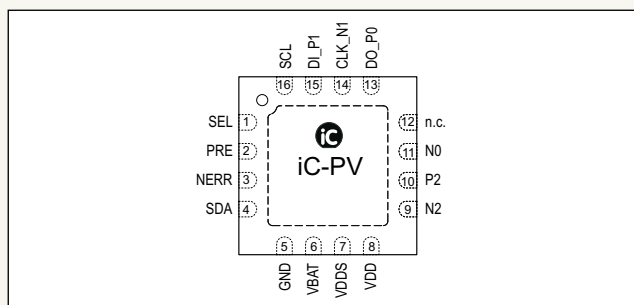
Operating Modes

| | |
|---|---|
| SSI Multiturn (9 to 40 bit) | for sensors with MT interface (iC-MHM, iC-MU, iC-LGC, iC-MN etc.) |
| Chain Multiturn (9 to 40 bit) with Singleturn Input (3 to 18 bit) | with synchronization of singleturns (iC-LNG, iC-LNB etc.) |
| Stand-alone SSI Multiturn (9 to 40 bit) | for battery-buffered metering applications |
| Parallel Singleturn (3 bit) | parallel complementary output (default op. mode w/o EEPROM) |

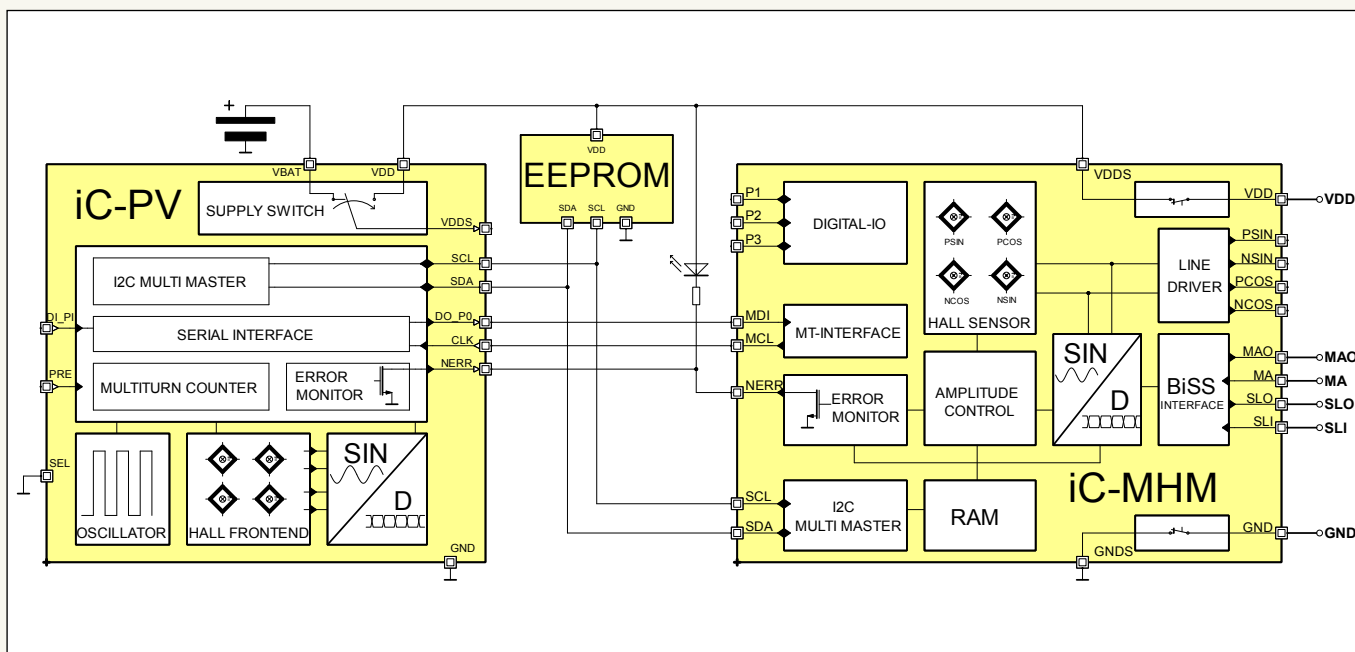
Pin Functions

| No. | Name | Function |
|-------|--------|---|
| 1 | SEL | Mode Select Pin |
| 2 | PRE | Preset Trigger Input |
| 3 | NERR | Error Message Output (active low) |
| 4 | SDA | EEPROM Interface, I ² C data line |
| 5 | GND | Ground |
| 6 | VBAT | Battery Supply Voltage Input (typ. 3.6 V) |
| 7 | VDDS | Switched Supply Voltage Output |
| 8 | VDD | +3.0 V to +5.5 V Supply Voltage Input |
| 9, 11 | N2, N0 | Parallel Output Bit 2, Bit 0 (negative logic) |
| 10 | P2 | Parallel Output Bit 2 (positive logic) |
| 12 | n.c. | not connected |
| 13 | DO_P0 | MT Interface, data outp. / Par. Output Bit 0 (pos.) |
| 14 | CLK_N1 | MT Interface, clock line / Par. Output Bit 1 (neg.) |
| 15 | DI_P1 | MT Interface, data input / Par. Output Bit 1 (pos.) |
| 16 | SCL | EEPROM Interface, I ² C clock Line |

Package QFN16 3 mm x 3 mm



Application Example



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